## Questions for exam from Numerical methods

- 1. Source and types of errors
- 2. Definition of absolute and relative errors, their estimation. Error of basic arithmetic operations.
- 3. Rounding, significant digits, significant decimal places. Show 5 examples.
- 4. Propagation of errors (illustrate on one example).
- 5. Representation of numbers, the smallest and the largest positive number, machine epsilon, underflow, overflow.
- 6. Conditionality of numerical problems, condition number, numerical stability of algorithms.
- 7. Briefly describe an algorithms for solution of nonlinear equation f(x) = 0.
- 8. Iterative method, the rate of convergence.
- 9. Bisection method, rate of convergence, pros and cons.
- 10. Regula falsi method, rate of convergence, pros and cons, compare with bisection method.
- 11. Secant method, rate of convergence, pros and cons.
- 12. Newton's method, rate of convergence, condition for convergence.
- 13. Explain the principle of fixed-point iteration method.
- 14. Aitken-Steffensen method, principle.
- 15. Achievable accuracy of the root.
- 16. Main methods for solution of system of linear equations. Brief characteristics.
- 17. Explain, why we should use Gaussian elimination with pivoting.
- 18. LU decomposition and its application.
- 19. Explain: "Gaussian elimination with pivoting assures the small residua."
- 20. Conditionality of problem to find solution of system of equations.
- 21. Cholesky decomposition.
- 22. Methods for calculation of determinant of matrix. Which method is suitable for determinants of matrices of high order?
- 23. When we use iterative method for solution of system of equations and why?
- 24. Briefly describe Jacobi method and compare with Gauss-Seidel method.
- 25. Basic principle of Krylov subspace methods, example.
- 26. Meaning of preconditioning.
- 27. Singular value decomposition, principle, application.
- 28. Approximation of functions
- 29. Lagrange polynomial, pros and cons.
- 30. Newton polynomial, pros and cons.
- 31. The error of approximation for interpolating polynomial. Optimal distribution of interpolation nodes.

- 32. Hermite interpolation, principle.
- 33. Spline interpolation, principle.
- 34. Linear spline interpolation, properties.
- 35. Hermite cubic spline, principle and properties.
- 36. Cubic spline, principle, boundary conditions, properties.
- 37. Least-square method, principle. Weighted least squares.
- 38. Normal equations, Gramian matrix and its condition number, selection of basis functions.

Example will consist of written preparation for answer to 4 questions and from oral answer to them and to other supplementary questions.

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